

Nested Pattern Unification

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Pattern Unification

$\alpha x_0 x_1 \dots x_n \stackrel{?}{=} \text{rhs}$ is solvable if

- 1 x_i are distinct bound vars.
- 2 rhs only depends on x_i bound vars.
- 3 α does not occur in rhs.

Then $\alpha := \lambda x_0 x_1 \dots x_n. \text{rhs}$.

All major dependently typed languages use pattern unification with some extensions.

Reduction to patterns

Reduce non-pattern problems to pattern ones. Examples:

① η -contraction:

$$\alpha (\lambda x. fx) \stackrel{?}{=} \text{rhs} \quad \Rightarrow \quad \alpha f \stackrel{?}{=} \text{rhs}$$

② Σ -elimination:

$$\begin{aligned} x : (a : A) \times B \vdash \alpha (\text{fst } x) &\stackrel{?}{=} \text{fst } x \\ \Rightarrow a : A, b : B \vdash \alpha a &\stackrel{?}{=} a \end{aligned}$$

$$\begin{aligned} \alpha : A \times B \rightarrow C \vdash \alpha (a, b) &\stackrel{?}{=} a \\ \Rightarrow \alpha' : A \rightarrow B \rightarrow C, \alpha := \text{uncurry } \alpha' \vdash \alpha' a b &\stackrel{?}{=} a \end{aligned}$$

Issues with reduction to patterns

η -contraction for Σ is expensive (needs conversion checks).

Σ -elimination is potentially expensive and unnecessarily η -long.

$\alpha(\lambda x y. f y x) \stackrel{?}{=} \text{rhs}$ is not reducible to a pattern problem.

Nested patterns

We directly solve a larger class of problems, called **nested pattern** problems.

Advantages:

- Conjecture: whenever f is a definitional isomorphism, $\alpha (fx) \stackrel{?}{=} x$ is solvable as $\alpha := f^{-1}$.
- A single pass on the spine and rhs is enough. No η -contraction, Σ -elimination or administrative metas are needed.

Implementations:

- <https://github.com/AndrasKovacs/sett>
- <https://gitlab.com/RafaelBocquet/obstt>

Algorithm

Basic idea:

- λ , pairing and projection is allowed in spines, recursively.
- In $\Gamma \vdash \alpha \text{ spine} \stackrel{?}{=} \text{rhs}$, rhs lives in Γ but the eventual solution is *closed* w.r.t. bound vars. So we need a substitution to make rhs depend only on the λ -bound vars in the solution.
- Recursing on the spine, we generate λ -s and pairings in the solution and also build the mentioned substitution.

It's not realistic to fully explain the algorithm in this talk so I'll focus on examples. I include a more detailed spec on the slides though.

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Here, pattern inversion yields $[x \mapsto a, y \mapsto b]$, and the solution is

$$\alpha := \lambda a b. x[x \mapsto a, y \mapsto b]$$

which is $\alpha := \lambda a b. a$.

Partial substitutions

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We generalize this to maps sending variables to certain *partial values*.

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- A formal TOP and a BOT value, both inhabiting any type.

Partial values have a partial ordering where TOP is top and BOT is bottom.

- If a meta solution contains TOP or BOT, that's a **unification error**.
- TOP signals an ambiguity from **non-linearity**, while BOT signals an **out-of-scope dependency**.

Informal examples (1)

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- We recurse on the spine, and the result will be under λa .
- The rest of the spine is empty, so we return rhs substituted with σ .
- Hence, the solution is $\lambda a. (\text{fst } x)[\sigma]$, that is, $\lambda a. a$.

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- Next, we do $\sigma := \sigma \sqcup [x \mapsto b]$.
- We get $[x \mapsto \text{TOP}]$ because the lub of distinct variables is TOP.
- Hence, the solution is $\lambda a b. \text{TOP}$, i.e. a non-linearity error.

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- This is a nested pattern problem!
- Note that f is OK here in head position, but e.g. x would not be!
- We'll see in the details later that *solvable* and *parameter* vars need to be distinguished.
- Recursive solving gets us $[f \mapsto \lambda b c. a c b]$.
- This gets lub-ed to the top σ , so we get $\lambda a b c. a c b$ as overall solution.

Specification (1/4)

solve tries to produce a solution for $\Gamma \vdash \alpha \text{ spine} \stackrel{?}{=} \text{rhs}$:

`solve Γ α sp rhs := solveSp Γ • [$x_i \mapsto \text{BOT}$] α sp rhs`

solveSp is a worker function that iterates through the spine and accumulates the partial substitution σ . Δ is the solution scope.

`solveSp Γ Δ σ α sp rhs`

invertArg tries to extend σ with the mapping $[t \mapsto a \text{ sp}']$. The problem scope Γ is split to three regions, “unsolvable” (Γ_u), “solvable” (Γ_s), and “parameters” (Γ_p). A nested pattern is only solvable if headed by a solvable variable.

`invertArg Γ_u Γ_s Γ_p Δ σ t (a sp')`

solveNestedSp produces a solution from a nested spine.

`solveNestedSp Γ_u Γ_s Γ_p Δ σ sp (a sp')`

Specification (2/4)

```
solve  $\Gamma$   $\alpha$  sp rhs = solveSp  $\Gamma$  • [ $x_i \mapsto \text{BOT}$ ] sp rhs
```

```
solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  [] rhs =  
  rhs[ $\sigma$ ,  $\alpha \mapsto \text{BOT}$ ]
```

```
solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  (app t :: sp) rhs =  
   $\lambda$  a. solveSp  $\Gamma$  ( $\Delta$ , a) (invertArg •  $\Gamma$  •  $\Delta$   $\sigma$  t (a []))  $\alpha$  sp rhs
```

```
solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  (fst :: sp) rhs =  
  (solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  sp rhs, freshMeta  $\Delta$ )
```

```
solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  (snd :: sp) rhs =  
  (freshMeta  $\Delta$ , solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  sp rhs)
```

```
solveSp  $\Gamma$   $\Delta$   $\sigma$   $\alpha$  _ rhs =  
  fail
```


Specification (3/4)

```
invertArg  $\Gamma_u \Gamma_s \Gamma_p \Delta \sigma$  (x sp) (a sp')  
  |  $x \in \Gamma_u \vee x \in \Gamma_p =$   
    fail  
  |  $x \in \Gamma_s =$   
     $\sigma \sqcup [x \mapsto \text{solveNestedSp } (\Gamma_u, \Gamma_s) \Gamma_p \bullet \Delta \sigma \text{ sp } (a \text{ sp}')] ]$ 
```

```
invertArg  $\Gamma_u \Gamma_s \Gamma_p \Delta \sigma$  (t, u) (a sp) =  
  let  $\sigma = \text{invertArg } \Gamma_u \Gamma_s \Gamma_p \Delta \sigma$  t (a (sp :: .fst)) in  
  invertArg  $\Gamma_u \Gamma_s \Gamma_p \Delta \sigma$  u (a (sp :: .snd))
```

```
invertArg  $\Gamma_u \Gamma_s \Gamma_p \Delta \sigma$  ( $\lambda x. t$ ) (a sp) =  
  invertArg  $\Gamma_u \Gamma_s (\Gamma_p, x) \Delta t$  (a (sp :: app x))
```

```
invertArg  $\Gamma_u \Gamma_s \Gamma_p \Delta \sigma$  _ (a sp) =  
  fail
```

Specification (4/4)

$\text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \Delta \sigma [] (a \text{ sp}') =$
 $a (sp'[\sigma])$

$\text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \sigma (\text{app } t :: sp) (a \text{ sp}') =$
 $\lambda a'. \text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p (\Delta, a')$
 $(\text{invertArg } \Gamma_u \Gamma_s \Gamma_p \Delta \sigma t (a' []))$
 $sp (a \text{ sp}')$

$\text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \sigma (\text{fst} :: sp) (a \text{ sp}') =$
 $(\text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \sigma sp (a \text{ sp}'), \text{BOT})$

$\text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \sigma (\text{snd} :: sp) (a \text{ sp}') =$
 $(\text{BOT}, \text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \sigma sp (a \text{ sp}'))$

$\text{solveNestedSp } \Gamma_u \Gamma_s \Gamma_p \sigma _ (a \text{ sp}') =$
 fail

Not explained here

- Integration into NbE.
- Implementation of partial substitution.
- Support for unit η and typed inversion.
- Analogous generalization of *pruning* where we can prune dependencies from inside nested Π/Σ types.